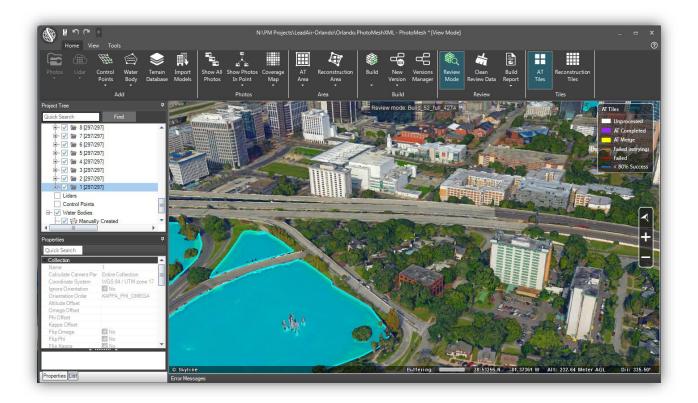


RELEASE NOTES FOR PHOTOMESH 7.6.1

About PhotoMesh

Skyline's PhotoMesh application fully automates the building of high-resolution, textured, 3D mesh models from oblique and nadir photographs and Lidar captured from street view, drones, UAV and airplanes. PhotoMesh's breakthrough technology is based on the highest-performance photogrammetry, computer vision, and computational geometry algorithms. PhotoMesh offers a range of output options including standard 3D model (3DML, OSGB, DAE, OBJ), raster (Orthophoto, DSM, DTM) and point cloud (LAS) formats. PhotoMesh's 3DML format can be transformed into powerful geospatial data that fully supports spatial operations and attribute queries, by loading it into TerraExplorer and merging it with classification information. All supported formats can be published from TerraExplorer Pro to SkylineGlobe Server for viewing in Skyline 3D viewers (TerraExplorer for Desktop, TerraExplorer for Web and TerraExplorer for Mobile) and 3rd party viewers (Cesium, ESRI, etc.).





New Features in Release 7.6.1

Bug Fixes and Improved Stability

This release improves overall stability and performance, and provides the following bug fixes:

- Changes to the coordinate system of a water body polygon or control point are saved and applied when reopening their project (APPS-3555).
- Memory usage is no longer increased when processing AT tiles in very large projects with significant number of AT tiles (APPS-3560).
- All selected build outputs are generated even when the 3DML build output is not selected (APPS-3586).
- Progress bar displays properly upon loading multiple Lidar files or a Lidar folder (APPS-3487).
- Generated multi-band orthophotos are now listed the Project Tree's Outputs folder (APPS-3361).
- Changes to fill color of added or imported water polygon are saved to project and applied when project is reopened (APPS-3557).
- Resolved bug that prevented project from opening when one of the project's outputs or build versions was manually deleted from the project folder (APPS-3525).
- Collection information is copied correctly to AT tile when using "Fully trusted AT input" (APPS-3499).
- Reconstruction of Lidar data and points generated from photos now works accurately on flat terrain (APPS-3550).
- Principal point is now calculated correctly for photos imported from Excel file (APPS-3479).
- Detailed report and property sheet now include the calculated Omega-Phi-Kappa values (APPS-3663).

New Features in Release 7.6

Quality Enhancements

- Improved mesh geometry for small objects, edges, cars, etc.
- Improved hole-filling algorithm
- Improved calculation of reconstruction tile height (to avoid tower cropping effect)
- Reduced geometry noise in small tiles

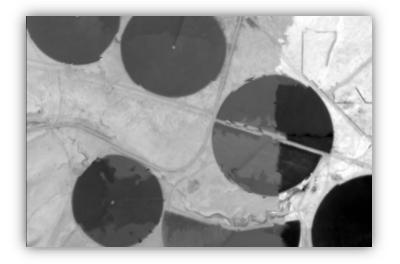




Multi-Band Support

New support for photos with multiple bands provides additional texturing options for 2D and 3D outputs.

- Define the bands available in each photo collection
- Select three bands for 3D model texturing (RGB, CIR, NIR, etc.)
- Select three or more bands for the orthophoto output



Improved Gigapixel Mechanism

New gigapixel mechanism allows you to pre-purchase a bank of gigapixel credits, load them to your local Skyline Floating License Server (SFLS), and automatically apply them towards different PhotoMesh projects to allow building of all output types without watermarks. Within a single project, multiple build versions can be created using the same gigapixel credits.

Production Automation

PhotoMesh 7.6 provides new API and automation tools:

- PhotoMesh API REST API to automate production phases, e.g., load photo files or list, set AT and reconstruction areas, begin and manage a build, and create new build versions. This robust API allows developers to automate PhotoMesh production flows on local machines and remote servers.
- ProjectQueue API REST API to create a project queue, and then activate, monitor, and manage the queue processing.

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Represent port						
http://iocalhost:8086 v						
BuildApi		~				
GET /Build/MaxPoolFusers	Returns the maximum number of fusers from the fusers pool set for this build.					
PUT /Build/MaxPoolFusers/	{maxPoolFusers} Sets the maximum number of fusers from the fusers pool to use for this build.					
GET /Build/MaxAWSFusers	Returns the maximum number of AWS fuser instances set to launch for this build.					
PUT /Build/MaxAWSFusers/{	maxANSFusers} Sets the maximum number of AWS fuser instances to launch for this build.					
GET /Build/Fusers Returns a	collection of all the fusers used in the build, and information on each.					
EventApi		~				
GET /Events/All						
ProjectApi		~				
GET /Project/Build/{Prese	tfile} Begins the build process, according to the build steps passed and the build parameters set in the preset file.					
Parameters		Try it out				
Name Description						
PresetFile * required straine The name of the	preset file to be loaded by PhotoMesh. The available preset files are in the Presets folder located under the PM Application Files folder, or					

Fusers Pool

 Auto-Scaling - PhotoMesh 7.6 enables you to share fusers between several PhotoMesh managers in your organization, to dynamically allocate and free fusers based on each project's resource needs. Each PhotoMesh Build Manager continuously monitors the fusers' progress and status and the processing requirements, and allocates or frees fusers as required.

Data Preparation Aerotri	angulation Reconstruction Tiles (Point Clouds, Me	Subnet ID:
Working Folder: Automatically use new available fusers:	C:\Users\Arik\Documents\PhotoMeshJobQueue Running AWS instances: 0 (Required: 0 max: 0).	Shutdown inactive fuser instance before the next billing hour Shutdown inactive fuser instances after: 10 Dee another AWS account
Auto Scaling <u>(Change)</u> : Fusers Online: 0 Use Fuser, Version Running Step	Running Pool fusers: 0 (Working: 0 max: 11). Selected: 0 Working: 0 Step Elansed Time Progress: Status	U Use Fusers Pool Fusers Pool Folder: V:\pool Change
ose roser version numming dep	There are currently no available fusers.	Fuser Folder: <mark>C:\Pzogram Files\Skyline\Phoso</mark> Chance. Retum inactive fuser to pool after: <mark>120 순</mark> seconds Maximum Fusers: 11 순
		OK Cancel

 Fusers Management Page - Provides centralized management of all the fusers in your organization so you can monitor them and their current tasks, and remotely move fusers from one project to another.

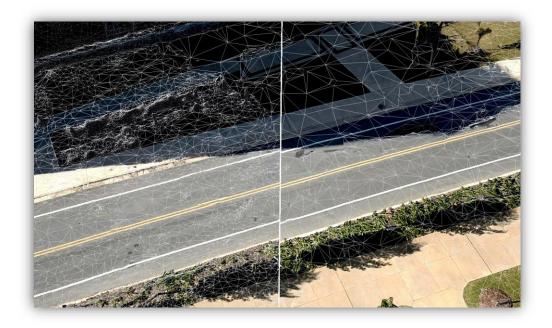
lanag	er: My Name	Pool: w:\pool		Working folder (UNC) c:\tmp			Fuser folder (UNC)	C:\Program Files\Sk	yline\PhotoMesh	
Refres	h Assign Set Idle Time	Private/Pool	Comment							
S	elect all									
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Improved I/O Performance

Improved input/output operations turbocharge performance in ultra-large-scale (100K+ photos) projects.

New Model Simplification Algorithm

Model simplification algorithm was rewritten to produce a simplified mesh model that uses less memory, without sacrificing model quality.

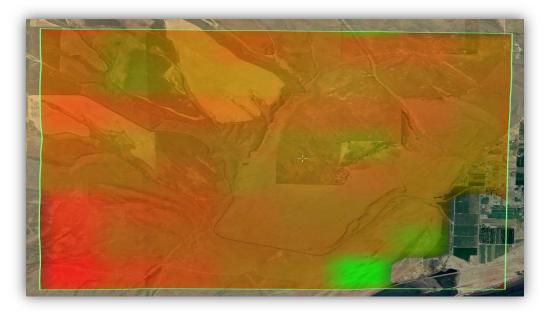


Cross-Platform Support

PhotoMesh Fuser 7.6 can now run on Linux as well as Windows operating systems. This is especially exciting news for users of cloud resources such as Amazon Web Services (AWS). PhotoMesh is currently supported on Ubuntu 16.04 and 18.04.

Connection Map

New addition to arsenal of tools for AT review makes it easy to evaluate the quality of the AT, based on the level of interconnection of the photos. Each point in the defined AT area is colored based on the percentage of interconnected photos out of all the photos that intersect with the point.



Improved Water Polygon Mechanism

- Expanded options allow you to easily create exactly the water body you need: whether it is a level
 water body such as a sea, lake, pond or pool (even on top of a non-flat terrain or mesh), or a water
 body with an elevation gradient such as a river.
- Import and work on several layers
- Supports vertical datums

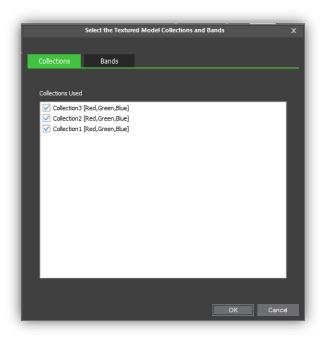
Collection Properties XML

Enables you to easily and quickly load photos and folders, either manually or using the API, and automatically apply a set of property definitions to these photos. The collectionProperties.xml includes only the collection definition and saves you the trouble of creating a full Excel or XML file that contains a list of all the photos.

Filter Collections for Reconstruction and Output

The filter collections option allows you to define the photos that you want for each step in the reconstruction and for the different outputs:

- Select and filter set of photo collections for the reconstruction phase
- Select and filter set of photo collections for the 3D model texturing
- Select and filter set of photo collections for the Orthophoto creation



Optimized Aerotriangulation Process

New settings provide better support for different data types and sensors:

- ECEF is now used as the default internal coordinate system to support large scale projects with no distortions
- New AT property defaults improve success rate when trying to solve projects from different sensors
- Matching results can be exported to Bingo

Revamped Tile Stitching Method

PM 7.6 features a new method of stitching tiles in the correct order to avoid gaps when rebuilding water polygons.

SOFTWARE AND HARDWARE REQUIREMENTS

Operating System	Windows [®] 7 / 8 / 10, Windows [®] Server 2012 R2 – 64-bit required.
System Memory	16 GB RAM (32 GB recommended).
Video Card	1GB of video memory (2GB or more recommended). Pixel and vertex shader v3.0.
Processor	4 cores (8 cores recommended). PhotoMesh works best in a multi-core environment and can utilize multiple CPU's and hyper-threaded processors.
Additional Software	.Net Framework 4.6 required.

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